

Operational semantics of programs

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Programs

We will consider a very simple programming language:

a	atomic action
$skip$	empty action
$\delta_1; \delta_2$	sequence
if ϕ then δ_1 else δ_2	if-then-else
while ϕ do δ	while-loop

As atomic action we will typically consider assignments:

$$x := v$$

As test any boolean condition on the current state of the memory.

Notice that our consideration extend to full-fledged programming language (as Java).

Program semantics

Programs are syntactic objects.

How do we assign a formal semantics to them?

Any idea of what the semantics should talk about?

Evaluation semantics

Idea: describe the overall result of the evaluation of the program.

Given a program δ and a memory state s compute the memory state s' obtained by executing δ in s .

More formally: Define the **relation**:

$$(\delta, s) \longrightarrow s'$$

where δ is a program, s is the memory state in which the program is evaluated, and s' is the memory state obtained by the evaluation.

Such a relation can be defined inductively in a standard way using the so called **evaluation (structural) rules**

Evaluation semantics: references

The general approach we follow is the *structural operational semantics* approach [Plotkin81, Nielson&Nielson99].

This whole-computation semantics is often called: *evaluation semantics* or *natural semantics* or *computation semantic*.

Evaluation rules for our programming constructs

$$\text{Act : } \frac{(a, s) \longrightarrow s'}{\text{true}} \quad \text{if } s \models \text{Pre}(a) \text{ and } s' = \text{Post}(a, s)$$

$$\text{special case: assignment } \frac{(x := v, s) \longrightarrow s'}{\text{true}} \quad \text{if } s' = s[x = v]$$

$$\text{Skip : } \frac{(\text{skip}, s) \longrightarrow s}{\text{true}}$$

$$\text{Seq : } \frac{(\delta_1; \delta_2, s) \longrightarrow s'}{(\delta_1, s) \longrightarrow s'' \wedge (\delta_2, s'') \longrightarrow s'}$$

$$\text{if : } \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow s'}{(\delta_1, s) \longrightarrow s'} \quad \text{if } s \models \phi \quad \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow s'}{(\delta_2, s) \longrightarrow s'} \quad \text{if } s \models \neg\phi$$

$$\text{while : } \frac{(\text{while } \phi \text{ do } \delta, s) \longrightarrow s}{\text{true}} \quad \text{if } s \models \neg\phi \quad \frac{(\text{while } \phi \text{ do } \delta, s) \longrightarrow s'}{(\delta, s) \longrightarrow s'' \wedge (\text{while } \phi \text{ do } \delta, s'') \longrightarrow s'} \quad \text{if } s \models \phi$$

Structural rules

The structural rules have the following schema:

$$\frac{\text{CONSEQUENT}}{\text{ANTECEDENT}} \text{ if SIDE-CONDITION}$$

which is to be interpreted logically as:

$$\forall(\text{ANTECEDENT} \wedge \text{SIDE-CONDITION} \supset \text{CONSEQUENT})$$

where $\forall Q$ stands for the universal closure of all free variables occurring in Q , and, typically, ANTECEDENT, SIDE-CONDITION and CONSEQUENT share free variables.

The structural rules define inductively a relation, namely: **the smallest relation satisfying the rules.**

Examples

Compute s_f in the following cases, assuming that in the memory state S_0 we have $x = 10$ and $y = 0$:

- $(x := x + 1; x := x * 2, S_0) \longrightarrow s_f$
- $(x := x + 1;$
 if $(x < 10)$ **then** $x := 0$ **else** $x := 1;$
 $x := x + 1,$
 $S_0) \longrightarrow s_f$
- $(y := 0; \mathbf{while} (y < 4) \mathbf{do} \{x := x * 2; y := y + 1\}, S_0) \longrightarrow s_f$

Transition semantics

Idea: describe the result of executing a **single step** of the program.

- *Given a program δ and a memory state s compute the memory state s' and the program δ' that remains to be executed obtained by executing a single step of δ in s .*
- *Assert when a program δ can be considered **successfully terminated** in a memory state s .*

Transition semantics (cont.)

More formally:

- Define the **relation**, named *Trans* and denoted by “ \longrightarrow ”):

$$(\delta, s) \longrightarrow (\delta', s')$$

where δ is a program, s is the memory state in which the program is executed, and s' is the memory state obtained by executing a single step of δ and δ' is what remains to be executed of δ after such a single step.

- Define a **predicate**, named *Final* and denoted by “ \checkmark ”):

$$(\delta, s) \checkmark$$

where δ is a program that can be considered (successfully) terminated in the memory state s .

Such a relation and predicate can be defined inductively in a standard way, using the so called **transition (structural) rules**

Transition semantics: references

The general approach we follow is the *structural operational semantics* approach [Plotkin81, Nielson&Nielson99].

This single-step semantics is often called: *transition semantics* or *computation semantics*.

Transition rules for our programming constructs

$$Act : \frac{(a, s) \longrightarrow (\epsilon, s')}{true} \quad \text{if } s \models Pre(a) \text{ and } s' = Post(a, s)$$

$$\text{special case: assignment } \frac{(x := v, s) \longrightarrow (\epsilon, s')}{true} \quad \text{if } s' = s[x = v]$$

$$Skip : \frac{(skip, s) \longrightarrow (\epsilon, s)}{true}$$

$$Seq : \frac{(\delta_1; \delta_2, s) \longrightarrow (\delta'_1; \delta_2, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \frac{(\delta_1; \delta_2, s) \longrightarrow (\delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s')} \quad \text{if } (\delta_1, s) \checkmark$$

$$if : \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow (\delta'_1, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \text{if } s \models \phi \quad \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s) \longrightarrow (\delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s')} \quad \text{if } s \models \neg \phi$$

$$while : \frac{(\text{while } \phi \text{ do } \delta, s) \longrightarrow (\delta'; \text{while } \phi \text{ do } \delta, s)}{(\delta, s) \longrightarrow (\delta', s')} \quad \text{if } s \models \phi$$

ϵ is the empty program.

Termination rules for our programming constructs

$$\epsilon : \frac{(\epsilon, s)^\vee}{true}$$

$$Seq : \frac{(\delta_1; \delta_2, s)^\vee}{(\delta_1, s)^\vee \wedge (\delta_2; s)^\vee}$$

$$if : \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s)^\vee}{(\delta_1, s)^\vee} \text{ if } s \models \phi \qquad \frac{(\text{if } \phi \text{ then } \delta_1 \text{ else } \delta_2, s)^\vee}{(\delta_2, s)^\vee} \text{ if } s \models \neg\phi$$

$$while : \frac{(\text{while } \phi \text{ do } \delta, s)^\vee}{true} \text{ if } s \models \neg\phi \qquad \frac{(\text{while } \phi \text{ do } \delta, s)^\vee}{(\delta, s)^\vee} \text{ if } s \models \phi$$

Structural rules

The structural rules have the following schema:

$$\frac{\text{CONSEQUENT}}{\text{ANTECEDENT}} \text{ if SIDE-CONDITION}$$

which is to be interpreted logically as:

$$\forall(\text{ANTECEDENT} \wedge \text{SIDE-CONDITION} \supset \text{CONSEQUENT})$$

where $\forall Q$ stands for the universal closure of all free variables occurring in Q , and, typically, ANTECEDENT, SIDE-CONDITION and CONSEQUENT share free variables.

The structural rules define inductively a relation, namely: **the smallest relation satisfying the rules.**

Examples

Compute δ', s' in the following cases, assuming that in the memory state S_0 we have $x = 10$ and $y = 0$:

- $(x := x + 1; x := x * 2, S_0) \longrightarrow (\delta', s')$
- **(if** $(x < 10)$ **then** $\{x := 0; y := 50\}$ **else** $\{x := 1; y := 100\};$
 $x := x + 1,$
 $S_0) \longrightarrow (\delta', s')$
- **(while** $(y < 4)$ **do** $\{x := x * 2; y := y + 1\}, S_0) \longrightarrow (\delta', s')$

Evaluation vs. transition semantics

How do we characterize a whole computation using single steps?

First we define the relation, named $Trans^*$, denoted by \longrightarrow^* by the following rules:

$$0 \text{ step : } \frac{(\delta, s) \longrightarrow^* (\delta, s)}{true}$$

$$n \text{ step : } \frac{(\delta, s) \longrightarrow^* (\delta'', s'')}{(\delta, s) \longrightarrow (\delta', s') \wedge (\delta', s') \longrightarrow^* (\delta'', s'')} \quad (\text{for some } \delta', s')$$

Notice that such relation is the **reflexive-transitive closure** of (single step) \longrightarrow .

Then it can be shown that:

$$(\delta, s_0) \longrightarrow s_f \equiv (\delta, s_0) \longrightarrow^* (\delta_f, s_f) \wedge (\delta_f, s_f) \checkmark \quad \text{for some } \delta_f$$

Examples

Compute s_f , using the definition based on \longrightarrow^* , in the following cases, assuming that in the memory state S_0 we have $x = 10$ and $y = 0$:

- $(x := x + 1; x := x * 2, S_0) \longrightarrow s_f$
- $(x := x + 1;$
 if $(x < 10)$ **then** $\{x := 0; y := 50\}$ **else** $\{x := 1; y := 100\};$
 $x := x + 1,$
 $S_0) \longrightarrow s_f$
- $(y := 0; \mathbf{while} (y < 4) \mathbf{do} \{x := x * 2; y := y + 1\}, S_0) \longrightarrow s_f$

Concurrency

The transition semantics extends immediately to constructs for concurrency: The evaluation semantics can still be defined but only in terms of the transition semantics (as above).

We model concurrent processes by **interleaving**: *A concurrent execution of two processes is one where the primitive actions in both processes occur, interleaved in some fashion.*

It is OK for a process to remain **blocked** for a while, the other processes will continue and eventually unblock it.

Constructs for concurrency

if ϕ **then** δ_1 **else** δ_2 ,

while ϕ **do** δ ,

$(\delta_1 \parallel \delta_2)$,

synchronized conditional

synchronized loop

concurrent execution

The constructs **if** ϕ **then** δ_1 **else** δ_2 and **while** ϕ **do** δ are the synchronized: *testing the condition ϕ does not involve a transition per se, the evaluation of the condition and the first action of the branch chosen are executed as an atomic unit.*

Similar to test-and-set atomic instructions used to build semaphores in concurrent programming.

Transition and termination rules for concurrency

$$\textit{transition} : \quad \frac{(\delta_1 \parallel \delta_2, s) \longrightarrow (\delta'_1 \parallel \delta_2, s')}{(\delta_1, s) \longrightarrow (\delta'_1, s')} \quad \frac{(\delta_1 \parallel \delta_2, s) \longrightarrow (\delta_1 \parallel \delta'_2, s')}{(\delta_2, s) \longrightarrow (\delta'_2, s')}$$

$$\textit{termination} : \quad \frac{(\delta_1 \parallel \delta_2, s)^\vee}{(\delta_1, s)^\vee \wedge (\delta_2, s)^\vee}$$