


SIəTIOIUOD pur saəłunoD


पวค1D


SIOJIӘ วฉలวJכ ҰOU SวOP



state timing




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$=0$
$\frac{2}{8}$
8
8
$\Omega$

midio

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mano






ISa $\uparrow$ aS $\downarrow$



Example

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## $\Rightarrow \cap \infty>$



| [1] | T1 | $\bigcirc$ | > | $\nabla$ | $\omega$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\stackrel{\Xi}{\Xi}$ | $\stackrel{\rightharpoonup}{\circ}$ | $\stackrel{\ominus}{\Xi}$ | $\stackrel{\circ}{0}$ | $8$ | $8$ | ${ }_{\sim}^{B}$ |
|  |  | $\begin{aligned} & \sum \\ & \frac{5}{5} \end{aligned}$ |  |  |  | \% |
| $\begin{aligned} & x \\ & \vdots \\ & \vdots \\ & 0 \end{aligned}$ |  | $\begin{aligned} & x \\ & \vec{\theta} \\ & \vec{\sim} \end{aligned}$ |  |  |  | $x$ |
|  | $\begin{aligned} & \underset{\sim}{\leftarrow} \\ & \underset{\sim}{E} \end{aligned}$ |  |  | $\stackrel{\longleftrightarrow}{\vec{n}}$ |  | $\ltimes$ |

